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9/20/2013 1 Emergency navigation among moving obstacles Zhiyong Wang Supervisor: Sisi Zlatanova OTB Research Institute for the Built Environment Delft University of

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knowledge based task level control including path planning, mission planning and control architecture and information B. T. Wang and Robert W. Brodersen

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Patent us8355818 - robots, systems, and methods

and autonomously repeats the sensing and moving to determine A hazard indicator corresponds to a robot position in the environment map and graphically

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Patent us7620477 - robotic intelligence kernel -

that includes a multi-level architecture and a dynamic autonomy structure. The multi-level architecture includes a robot behavior level for defining robot

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Patent us8271132 - system and method for seamless

and modify task designators on the environment map. The task designators indicate a position in the environment map and indicate a task for the robot to achieve.

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