

# Path Planning For First Responders In The Presence Of Moving Obstacles (A+BE | Architecture And The Built Environment) By Zhiyong Wang

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first responders are hesitant to interact with others for obstacle avoidance and path planning based on real built environment

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### **Taxonomy of navigation for first responders -**

Taxonomy of Navigation for First Responders first responders among both static and moving obstacles. sensing solutions for the built environment.

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### **Patent us8355818 - robots, systems, and methods**

and autonomously repeats the sensing and moving to determine A hazard indicator corresponds to a robot position in the environment map and graphically

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### **A hybrid heuristics and simulation-based approach**

A Hybrid Heuristics and Simulation-Based Approach to Decision Support for Robot-Human Team Configuration: HEURISTICS -- PLANNING -- PROGRESSIVE -- REFINEMENT

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### **Large scale simulation for human evacuation and**

Ultrasonic sensors can range the distance to obstacles in the environment, first responders and emergency path planning for sensor

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2012 as Dean Feniosky Pe a-Mora efficient collaboration among first responders. an environment, the as-built interior construction objects

### **Planning under uncertainty and constraints for**

Planning under uncertainty and constraints for teams of Unmanned vehicles can complement human first responders by performing tasks that do not require

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and some of them show the ability to guide first responders around the for Navigation Among Moving Obstacles for the Built Environment,

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that it needs to perform path planning in the presence of moving First Responders and robot developers tried agent architecture for

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### **Patent us8271132 - system and method for seamless**

and modify task designators on the environment map. The task designators indicate a position in the environment map and indicate a task for the robot to achieve.

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### **2009 publications | ncd.gov**

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### **Issuu - aeroastro annual 8 by mit**

AeroAstro Annual 8. static and/ or predictably-moving obstacles, but planning safe paths around objects with be transmitted to first-responders,

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### **Patent us7620477 - robotic intelligence kernel -**

that includes a multi-level architecture and a dynamic autonomy structure. The multi-level architecture includes a robot behavior level for defining robot

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### **Patent us8073564 - multi-robot control interface -**

These maps also may be shared with other robots or human first responders. global path planning to moves through its environment, or built by a combination of

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TU Delft Ph.D. thesis series Architecture and the Built Environment. Path planning for first responders in the presence of moving obstacles. Zhiyong Wang.

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### **Patent us7801644 - generic robot architecture -**

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Path planning to help emergency responders avoid moving obstacles; of the built environment and for Zhiyong Wang: Path planning for first responders

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mission is to support our citizens and first responders to ensure that as FEMA Strategic Plan; Former Administrators; Mission Support; in the FEMA App

### **Emergency navigation among moving obstacles - tu**

9/20/2013 1 Emergency navigation among moving obstacles Zhiyong Wang Supervisor: Sisi Zlatanova OTB Research Institute for the Built Environment Delft University of

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potential algorithm for predicting probability of collision with stationary or moving obstacles; visual environment FEMA) first responders to

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